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◆ **Acknowledgements:** This work was supported in part by the National Science Foundation of China under Grants 61522207 and 61473231.

We performe dimensionality reduction and graph construction simultaneously. Both the optimal graph and the projection matrix can be obtained.

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Motivations & Contributions

Linear Manifold Regularization with Adaptive Graph for Semi-supervised Dimensionality Reduction Kai Xiong, Feiping Nie, Junwei Han

u **Two Issues of graph-based methods**

We consider the probabilistic neighbors to learn the similarity matrix *S*, and we simply have s_{ii} =0.

- 1. Most existing graph-based methods perform dimensionality reduction and graph construction separately.
- 2. One usually constructs a graph by KNN criteria. However, due to the noise and redundant information in the original data, such ^a pre-defined graph has no clear structure.

u **Our Contributions**

$$
\min_{W,b} \gamma_A \|W\|_F^2 + \gamma_I Tr(W^T X L X^T W) + \frac{1}{l} \sum_{i=1}^l \|W^T x_i + b - y_i\|^2.
$$

◆ Adaptive Neighbor Learning (ANL)

- \triangleright the optimal *F* is formed by the eigenvectors of *L* corresponding to the first *c* smallest eigenvalues.
- \triangleright The optimal W and b can be obtained by setting the derivatives of the objective equal to zero, respectively.
- \triangleright It is independent to learn s_i for each sample. The quadratic problem with linear constraint has closed form solution. [Huang et al., 2015]
- \triangleright Initialization: We learn an initial graph by ANL. The parameter γ can be initialized adaptively, and λ can be tuned dynamically.

Experimental Results

$$
\min_{s_i^T} \min_{1=1, 0 \le s_{ij} \le 1} \sum_{i,j=1}^n (||x_i - x_j||_2^2 s_{ij} + \gamma s_{ij}^2).
$$

Formulation of LMRAG

 $,j=1$

 $i, j=1$

 $1=1, \frac{1}{i} = 1$

*n*₁₁

 \min_{x} \sum_{i} $\|W^{T}x\|$

 T_{1-1} \leftarrow

 $\sum_{n=-\infty}^{J,\infty}$ 1-1, $i, j=1$ $\geq 0, S^T 1 = 1, \ldots$

 $(L)=n-c$

 $, b, S \geq 0, S'$ 1=1, $, \underline{\hspace{1cm}}$

 $rank(L)=n-c$ $l, J-1$

 $W, b, S \ge 0, S'$ 1=1, $\sum_{i=1}$

 \triangleright *U* is a diagonal matrix that picks out the labeled data. σ_i is the *i*-th smallest eigenvalue of *L*. *F* is a kind of embedding of *X*.

- \triangleright The first term of the objective function is acturally conducting ANL in the projected space.
- Ø The multiplicity of eigenvalue zero of graph Laplacian *L* is equal to the number of connected components in the graph. Thus we can take the rank constraint as a structure constraint.
- \triangleright The graph and the projection matrix can be both optimized.

References & Acknowledgments

We take linear Laplacian regularized least squares (LapRLS/L) as an example to briefly introduce LMR.

i

 T_{∞} *M_I*

2 $\sqrt{||\mathbf{r}||^2}$ 1

 $\|\gamma\|_{E}^{2} + \beta \|W\|_{E}^{2}$ | |

 F *F* $\|F\|$ **F**

2 \qquad \q

2 $\frac{y}{x}$ $\frac{z}{x}$

 \iiint_{2} ^{*i*} *ij* \iint

 T_{∞} \parallel^2 \sim \parallel

Table 1 Classification Accuracy (Part of the results)

 $+ \alpha Tr(W^T X + b1^T - Y)U(W^T X + b1^T - Y)^T + 2\lambda Tr(FLF^T)$

- We take the rank constraint to learn a structured graph. The learned graph is also sparse.
- 3. A simple algorithm is derived for the problem with rank constraint.
Extensive experiments demonstrate its effectiveness.

Notations & Background

- \triangleright Notations: $X \in \mathbb{R}^{d \times n}$ is the data matrix, where the first *l* samples are labeled and the last *u* samples are unlabeled. $Y \in \mathbb{R}^{c \times n}$ is the label matrix defined as y_{ji} =1 if x_i has label *j* and y_{ji} =0, otherwise. $W \in \mathbb{R}^{d \times c}$ is the projection matrix. *L* is the graph Laplacian and *S* is the similarity matrix. The *i*-th column of matrix *M* is m_i , and the (i, j) -th entry is m_{ij} .
- \blacklozenge Linear Manifold Regularization (LMR)

Ø Incorporate ANL into LMR. Take the rank constratint as a structure constraint.

$$
\sum_{i=1}^{n} \sigma_i = \min_{\text{constant.}} \text{Tr}(FLF^T)
$$
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$$
\sum_{i=1}^{n} \sigma_i = \min_{FF^T = I_c} \text{Tr}(FLF^T)
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\sum_{i=1}^{n} \sigma_i = \min_{FF^T = I_c} \text{Tr}(FLF^T)
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$$
\sum_{i=1}^{n} \sigma_i = \min_{FF^T = I_c} \text{Tr}(FLF^T)
$$

60 $20[°]$ (f) Adaptive graph (d) KNN graph (e) Initial graph

Figure 1. Practical illustrations Figure 2. Parameter effect

Ø Comparison methods: (1) SDA [Cai et al., 2007]. (2) TR-FSDA [Huang et al., 2012]. (3) SSDL [Gao et al., 2015]. (4) FME [Nie et al., 2010], and (5) LapRLS/L [Sindhwani et al., 2005].

(a) KNN graph (b) Initial graph (c) Adaptive graph

(b) CMU PIE (U) (c) YALE-B (U) (a) Corel (U)

Poster Presenter: Kai Xiong (bearkai1992@gmail.com). Research Interest: ML.

I am supposed to get my master's degree in March next year, and I'm looking for a job now.